# INTRODUCTION TO LIE ALGEBRAS. LECTURE 1.

1. Algebras. Derivations. Definition of Lie Algebra

1.1. Algebras. Let k be a field. An algebra over k (or k-algebra) is a vector space A endowed with a bilinear operation

$$a, b \in A \mapsto a \cdot b \in A.$$

Recall that bilinearity means that for each  $a \in A$  left and right multiplications by a are linear transformations of vector spaces (i.e. preserve sum and multiplication by a scalar).

### 1.1.1. Some extra properties

An algebra A is called associative if  $a \cdot (b \cdot c) = (a \cdot b) \cdot c)$ . An algebra A is commutative if  $a \cdot b = b \cdot a$ .

Usually commutative algebras are supposed to be associative as well.

#### 1.1.2. Example

If V is a vector space,  $\operatorname{End}(V)$ , the set of (linear) endomorphisms of V is an associative algebra with respect to composition. If  $V = k^n$  $\operatorname{End}(V)$  is just the algebra of  $n \times n$  matrices over k.

**1.1.3.** Example The ring of polynomials k[x] over k is a commutative k-algebra. The same for  $k[x_1, \ldots, x_n]$ , the algebra of polynomials of n variables.

#### 1.1.4. Example

If V is a vector space, define an operation by the formula

$$a \cdot b = 0.$$

This is an algebra operation.

1.2. Subalgebras, ideals, quotient algebras. A linear map  $f : A \to B$  of k-algebras is called homomorphism if  $f(a \cdot b) = f(a) \cdot f(b)$  for each  $a, b \in A$ .

The image of a homomorphism is a *subalgebra* (please, give a correct definition). Kernel of f defined as  $\{a \in A | f(a) = 0\}$  is an ideal in A. Here are the appropriate definitions.

$$a, b \in B \Longrightarrow a \cdot b \in B.$$

**Definition 1.2.1.** A vector subspace  $B \subseteq A$  is called a subalgebra if

**Definition 1.2.2.** A vector subspace  $I \subseteq A$  is called an ideal if

$$a \in A\&x \in I \Longrightarrow a \cdot x \in I\&x \cdot a \in I$$

**Lemma 1.2.3.** Let  $f : A \to B$  be a homomorphism of algebras. Then Ker(f) is an ideal in A.

*Proof.* Exercise.

An important property of ideals is that one can form a quotient algebra "modulo I". Here is the construction.

Let A be an algebra and I an ideal in A. We define the quotient algebra A/I as follows.

As a set this is the quotient of A modulo the equivalence relation

$$a \sim b$$
 iff  $a - b \in I$ .

Thus, this is the set of equivalence classes having form a + I, where  $a \in A$ .

Structure of vector space on A/I is given by the formulas

$$(a + I) + (b + I) = (a + b) + I; \quad \lambda(a + I) = \lambda a + I.$$

Algebra structure on A/I is given by the formula

$$(a+I)\cdot(b+I) = a\cdot b + I.$$

One has a canonical homomorphism

$$\rho: A \longrightarrow A/I$$

defined by the formula  $\rho(a) = a + I$ .

As usual, the following theorem (Theorem on homomorphism) is straighforward.

**Theorem 1.2.4.** Let  $f : A \longrightarrow B$  be a homomorphism of algebras and let I be an ideal in A. Suppose that  $I \subseteq \text{Ker}(f)$ . Then there exists a unique homomorphism  $\overline{f} : A/I \longrightarrow B$  such that  $f = \overline{f} \circ \rho$  where  $\rho : A \longrightarrow A/I$  is the canonical homomorphism.

Moreover,  $\overline{f}$  is onto iff f is onto;  $\overline{f}$  is one-to-one iff I = Ker(f).

Proof. Exercise.

$$d(a \cdot b) = d(a) \cdot b + a \cdot d(b).$$

The set of all derivations of A is denoted Der(A). This is clearly a vector subspace of End(A).

**1.3.1.** Composition Let  $d, d' \in Der(A)$  let us check that the composition dd' is not a derivation.

(1) 
$$dd'(a \cdot b) = d(d'(a) \cdot b + a \cdot d'(b)) = d(d'(a) \cdot b) + d(a \cdot d'(b)) = dd'(a) \cdot b + d'(a) \cdot d(b) + d(a) \cdot d'(b) + a \cdot dd'(b)$$

which is not exactly what we need.

**1.3.2.** Bracket Thus, we suggest another operation. Given  $d, d' \in Der(A)$ , define [d, d'] = dd' - d'd.

**Theorem 1.3.3.** If  $d, d' \in Der(A)$  then  $[d, d'] \in Der(A)$ .

*Proof.* Direct calculation.

## 1.3.4. Properties of this bracket

1. [x, x] = 0.

2. (Jacobi identity) [[xy]z] + [[zx]y] + [[yz]x] = 0Exercise: check this.

1.4. **Definition of Lie algebra. First examples.** A Lie algebra is an algebra with an operation satisfying the properties 1.3.

The operation in a Lie algebra is usually denoted [,] and called (Lie) bracket.

**1.4.1.** Anticommutativity The first property of a Lie algebra saying [xx] = 0 is called anticommutativity. In fact, it implies that [xy] = -[yx] for all x, y.

Proof: 0 = [x + y, x + y] = [xx] + [xy] + [yx] + [yy]. This implies [xy] = -[yx]. The converse is true if char  $k \neq 2$ . In fact, [xx] = -[xx] implies that 2[xx] = 0 and, if the characteristic of k is not 2, this implies [xx] = 0.

**1.4.2.** Example Let  $k = \mathbb{R}$ ,  $L = \mathbb{R}$ . We are looking for possible Lie brackets on L. Bilinearity and anticommutativity require

$$[a,b] = [a \cdot 1, b \cdot 1] = ab[1,1] = 0.$$

Thus, there is only one Lie bracket on  $L = \mathbb{R}$ .

**Definition 1.4.3.** A Lie algebra L having a zero bracket is called *a* commutative Lie algebra.

**1.4.4.** Observation Fix a field k of characteristic  $\neq 2$  and let  $L = \langle e_1, \ldots, e_n \rangle$  be n-dimensional vector space over k. In order to define a bilinear operation, it is enough to define it on  $e_i$ :

$$[e_i, e_j] = \sum_{k=1}^n c_{ij}^k e_k.$$

(this is true for any type of algebra). Elements  $c_{ij}^k$  are called *structure* constants of L.

Since we want the bracket to be anti-commutative, one has to have

$$[e_i, e_j] = [e_j, e_i].$$

Bilinearity and this condition imply anti-commutativity of the bracket (check this formally!).

Suppose now we have checked already anticommutativity. To check Jacobi identity let us denote

$$J(x, y, z) = [[xy]z] + [[zx]y] + [[yz]x].$$

One observes that J is trilinear (linear on each one of its three arguments) and antisymmetric (it changes sign if one interchanges any two arguments).

Thus, in order to check J(x, y, z) is identically zero, it is enough to check

$$J(e_i, e_j, e_k) = 0$$
 for  $1 \le i < j < k \le n$ .

**1.4.5.** Example Suppose dim L = 2. Suppose L is not commutative. Choose a basis  $L = \langle e_1, e_2 \rangle$ . One has

$$[e_1, e_1] = [e_2, e_2] = 0$$
 and  $[e_1, e_2] = -[e_2, e_1].$ 

Let  $[e_1, e_2] = y$ . Then  $y \neq 0$  and any bracket in L is proportional to y (by bilinearity).

Thus, it is convenient to take y as one of generators on L. Choose another one, say x. We have  $L = \langle x, y \rangle$  and  $[x, y] = \lambda y$ . Since L is not commutative,  $\lambda \neq 0$ . Thus change variables once more setting  $x := x/\lambda.$ 

We finally get

(2) 
$$L = \langle x, y \rangle$$
 and  $[x, y] = y$ 

We have therefore proven that there are only two two-dimensional Lie algebras over k up to isomorphism: a commutative Lie algebra and the one described in (2).

**1.4.6.** Example The set of  $n \times n$  matrices over k is an associative algebra with respect to the matrix multiplication. It becomes a Lie algebra if we define a bracket by the formula

$$[x,y] = xy - yx.$$

This Lie algebra is denoted  $\mathfrak{gl}_n(k)$  (sometimes we do not mention the field k). Its dimension is, of course,  $n^2$ .

The Lie algebra  $\mathfrak{gl}_n$  admits a remarkable Lie subalgebra.

Define  $\mathfrak{sl}_n = \{a \in \mathfrak{gl}_n | \operatorname{tr}(a) = 0\}.$ Here  $\operatorname{tr}(a) = \sum a_{ii}$  is the trace of a, the sum of the diagonal elements of a.

We claim this is a Lie subalgebra.

# 1.4.7. Proof

Recall that for each pair of matrices a, b one has

$$\operatorname{tr}(ab) = \operatorname{tr}(ba).$$

(Proof is just a direct calculation: both sides are equal to  $\sum_{ij} a_{ij} b_{ji}$ .)

Then tr([a, b]) = tr(ab) - tr(ba) = 0. This proves that  $\mathfrak{sl}_n$  is closed under the bracket operation.